1	RADIO WAVE ABSORBER	26 C	.Mounted on ship (EPO)
2	.For aircraft or missile	26 D	.Ground based (EPO)
3	.For camouflage	27	PRESENCE DETECTION ONLY
4	.With particular geometric	28	.By motion detection
•	configuration	29	AIRCRAFT COLLISION AVOIDANCE
5	RADAR REFLECTOR		SYSTEM (CAS)
6	.With modulation	30	.With transponder
7	.Corner	31	Including synchronized clock
8	Inflatable or collapsable	32	Included in Secondary
9	Decoy or tow target		Surveilance Radar (SSR) or Air
10	.Inflatable or collapsable		Traffic Control Radio Beacon
11	.With spherical lens (e.g.,		System (ATCRBS)
	Luneberg lens)	33	AIRCRAFT LANDING SYSTEM
12	.Chaff	34	.Ground control approach (GCA)
13	RADAR EW (ELECTRONIC WARFARE)	35	.Microwave landing system (MLS)
14	.ECM (Electronic countermeasures,	36	AIR TRAFFIC CONTROL
	i.e., jamming)	37	.Secondary Surveilance Radar
15	With repeater		(SSR) or Air Traffic Control
16	.ECCM (Electronic counter-	2.0	Radar Beacon System (ATCRBS)
	countermeasures, i.e.,	38	With altitude information
	antijamming)	39	With side lobe suppression
17	Radar reacts to jamming	40	With defruiting or degarbling
18	By changing frequency	41	SHIP COLLISION AVOIDANCE
19	By varying gain or blocking	42 43	RADAR TRANSPONDER SYSTEM
	receiver	43	.Combined with primary radar
20	.Detection of surveilance	44	system .Unique identity
21	BASE BAND SYSTEM	45	.IFF or SIF
22	TRANSMISSION THROUGH MEDIA OTHER	46	.Navigational
	THAN AIR OR FREE SPACE	47	Distance measuring equipment
23	BERTHING OR DOCKING	± ,	Dibeance meabaiing equipment
0.4	D. T. T. D. D. T. D.		(DME)
24 25 D	BLIND AID	48	(DME)With automatic lock-on
25 R	SYNTHETIC APERTURE RADAR	48 49	(DME)With automatic lock-onWith VOR/TACAN
	SYNTHETIC APERTURE RADAR .Mapping or imaging using		With automatic lock-onWith VOR/TACAN
25 R 25 A	SYNTHETIC APERTURE RADAR .Mapping or imaging using synthetic aperture radar (EPO)	49	With automatic lock-onWith VOR/TACAN .With Telemetry
25 R	SYNTHETIC APERTURE RADAR .Mapping or imaging using synthetic aperture radar (EPO) Specially adapted for moving	49 50	With automatic lock-onWith VOR/TACAN
25 R 25 A 25 B	SYNTHETIC APERTURE RADAR .Mapping or imaging using synthetic aperture radar (EPO) Specially adapted for moving target detection (EPO)	49 50 51	With automatic lock-onWith VOR/TACAN .With Telemetry .Radar transponder only
25 R 25 A	SYNTHETIC APERTURE RADAR .Mapping or imaging using synthetic aperture radar (EPO) .Specially adapted for moving target detection (EPO) Combined with monopulse or	49 50 51	With automatic lock-onWith VOR/TACAN .With Telemetry .Radar transponder only COMBINED WITH DIVERSE TYPE
25 R 25 A 25 B 25 C	SYNTHETIC APERTURE RADAR .Mapping or imaging using synthetic aperture radar (EPO) Specially adapted for moving target detection (EPO) Combined with monopulse or interferometric (EPO)	49 50 51 52	With automatic lock-onWith VOR/TACAN .With Telemetry .Radar transponder only COMBINED WITH DIVERSE TYPE RADIANT ENERGY SYSTEM
25 R 25 A 25 B	SYNTHETIC APERTURE RADAR .Mapping or imaging using synthetic aperture radar (EPO) Specially adapted for moving target detection (EPO) Combined with monopulse or interferometric (EPO) With frequency domain	49 50 51 52	With automatic lock-onWith VOR/TACAN .With Telemetry .Radar transponder only COMBINED WITH DIVERSE TYPE RADIANT ENERGY SYSTEM .With infrared device
25 R 25 A 25 B 25 C	SYNTHETIC APERTURE RADAR .Mapping or imaging using synthetic aperture radar (EPO) Specially adapted for moving target detection (EPO) Combined with monopulse or interferometric (EPO) With frequency domain processing of the SAR signals	49 50 51 52 53 54	With automatic lock-onWith VOR/TACAN .With Telemetry .Radar transponder only COMBINED WITH DIVERSE TYPE RADIANT ENERGY SYSTEM .With infrared device .With laser
25 R 25 A 25 B 25 C	SYNTHETIC APERTURE RADAR .Mapping or imaging using synthetic aperture radar (EPO) Specially adapted for moving target detection (EPO) Combined with monopulse or interferometric (EPO) With frequency domain	49 50 51 52 53 54 55	With automatic lock-onWith VOR/TACAN .With Telemetry .Radar transponder only COMBINED WITH DIVERSE TYPE RADIANT ENERGY SYSTEM .With infrared device .With laser .With television
25 R 25 A 25 B 25 C 25 D	SYNTHETIC APERTURE RADAR .Mapping or imaging using synthetic aperture radar (EPO) Specially adapted for moving target detection (EPO) Combined with monopulse or interferometric (EPO) With frequency domain processing of the SAR signals in azimuth (EPO)	49 50 51 52 53 54 55 56	With automatic lock-onWith VOR/TACAN .With Telemetry .Radar transponder only COMBINED WITH DIVERSE TYPE RADIANT ENERGY SYSTEM .With infrared device .With laser .With television .With direction finding
25 R 25 A 25 B 25 C 25 D	SYNTHETIC APERTURE RADAR .Mapping or imaging using synthetic aperture radar (EPO) Specially adapted for moving target detection (EPO) Combined with monopulse or interferometric (EPO) With frequency domain processing of the SAR signals in azimuth (EPO) With time domain processing of	49 50 51 52 53 54 55 56 57	With automatic lock-onWith VOR/TACAN .With Telemetry .Radar transponder only COMBINED WITH DIVERSE TYPE RADIANT ENERGY SYSTEM .With infrared device .With laser .With television .With direction finding .With radio voice communication
25 R 25 A 25 B 25 C 25 D	Mapping or imaging using synthetic aperture radar (EPO)Specially adapted for moving target detection (EPO)Combined with monopulse or interferometric (EPO)With frequency domain processing of the SAR signals in azimuth (EPO)With time domain processing of the SAR signals in azimuth,	49 50 51 52 53 54 55 56 57	With automatic lock-onWith VOR/TACAN .With Telemetry .Radar transponder only COMBINED WITH DIVERSE TYPE RADIANT ENERGY SYSTEM .With infrared device .With laser .With television .With direction finding .With radio voice communication .With transmission to a remote
25 R 25 A 25 B 25 C 25 D 25 E	Mapping or imaging using synthetic aperture radar (EPO)Specially adapted for moving target detection (EPO)Combined with monopulse or interferometric (EPO)With frequency domain processing of the SAR signals in azimuth (EPO)With time domain processing of the SAR signals in each time focusing (EPO)	49 50 51 52 53 54 55 56 57 58	With automatic lock-onWith VOR/TACAN .With Telemetry .Radar transponder only COMBINED WITH DIVERSE TYPE RADIANT ENERGY SYSTEM .With infrared device .With laser .With television .With direction finding .With radio voice communication .With transmission to a remote station
25 R 25 A 25 B 25 C 25 D 25 E	Mapping or imaging using synthetic aperture radar (EPO)Specially adapted for moving target detection (EPO)Combined with monopulse or interferometric (EPO)With frequency domain processing of the SAR signals in azimuth (EPO)With time domain processing of the SAR signals in azimuth, e.g. time focusing (EPO)Particular SAR processing	49 50 51 52 53 54 55 56 57 58	With automatic lock-onWith VOR/TACAN .With Telemetry .Radar transponder only COMBINED WITH DIVERSE TYPE RADIANT ENERGY SYSTEM .With infrared device .With laser .With television .With direction finding .With radio voice communication .With transmission to a remote station PLURAL RADAR TRANSMITTING INTELLIGENCE RETURN SIGNAL CONTROLS EXTERNAL
25 R 25 A 25 B 25 C 25 D 25 E	SYNTHETIC APERTURE RADAR .Mapping or imaging using synthetic aperture radar (EPO) Specially adapted for moving target detection (EPO) Combined with monopulse or interferometric (EPO) With frequency domain processing of the SAR signals in azimuth (EPO) With time domain processing of the SAR signals in azimuth, e.g. time focusing (EPO) Particular SAR processing techniques (e.g., squint mode, doppler beam-sharpening mode, spotlight mode, bistatic SAR,	49 50 51 52 53 54 55 56 57 58 59 60 61	With automatic lock-onWith VOR/TACAN .With Telemetry .Radar transponder only COMBINED WITH DIVERSE TYPE RADIANT ENERGY SYSTEM .With infrared device .With laser .With television .With direction finding .With radio voice communication .With transmission to a remote station PLURAL RADAR TRANSMITTING INTELLIGENCE RETURN SIGNAL CONTROLS EXTERNAL DEVICE
25 R 25 A 25 B 25 C 25 D 25 E 25 F	Mapping or imaging using synthetic aperture radar (EPO)Specially adapted for moving target detection (EPO)Combined with monopulse or interferometric (EPO)With frequency domain processing of the SAR signals in azimuth (EPO)With time domain processing of the SAR signals in azimuth, e.g. time focusing (EPO)Particular SAR processing techniques (e.g., squint mode, doppler beam-sharpening mode, spotlight mode, bistatic SAR, inverse SAR) (EPO)	49 50 51 52 53 54 55 56 57 58 59 60 61	With automatic lock-onWith VOR/TACAN .With Telemetry .Radar transponder only COMBINED WITH DIVERSE TYPE RADIANT ENERGY SYSTEM .With infrared device .With laser .With television .With direction finding .With radio voice communication .With transmission to a remote station PLURAL RADAR TRANSMITTING INTELLIGENCE RETURN SIGNAL CONTROLS EXTERNAL DEVICE .Missile or spacecraft guidance
25 R 25 A 25 B 25 C 25 D 25 E	Mapping or imaging using synthetic aperture radar (EPO)Specially adapted for moving target detection (EPO)Combined with monopulse or interferometric (EPO)With frequency domain processing of the SAR signals in azimuth (EPO)With time domain processing of the SAR signals in azimuth, e.g. time focusing (EPO)Particular SAR processing techniques (e.g., squint mode, doppler beam-sharpening mode, spotlight mode, bistatic SAR, inverse SAR) (EPO) RADAR FOR METEOROLOGICAL USE	49 50 51 52 53 54 55 56 57 58 59 60 61 62 63	With automatic lock-onWith VOR/TACAN .With Telemetry .Radar transponder only COMBINED WITH DIVERSE TYPE RADIANT ENERGY SYSTEM .With infrared device .With laser .With television .With direction finding .With radio voice communication .With transmission to a remote station PLURAL RADAR TRANSMITTING INTELLIGENCE RETURN SIGNAL CONTROLS EXTERNAL DEVICE .Missile or spacecraft guidance .Aircraft guidance
25 R 25 A 25 B 25 C 25 D 25 E 25 F	Mapping or imaging using synthetic aperture radar (EPO)Specially adapted for moving target detection (EPO)Combined with monopulse or interferometric (EPO)With frequency domain processing of the SAR signals in azimuth (EPO)With time domain processing of the SAR signals in azimuth, e.g. time focusing (EPO)Particular SAR processing techniques (e.g., squint mode, doppler beam-sharpening mode, spotlight mode, bistatic SAR, inverse SAR) (EPO) RADAR FOR METEOROLOGICAL USE (EPO)	49 50 51 52 53 54 55 56 57 58 59 60 61 62 63 64	With automatic lock-onWith VOR/TACAN .With Telemetry .Radar transponder only COMBINED WITH DIVERSE TYPE RADIANT ENERGY SYSTEM .With infrared device .With laser .With television .With direction finding .With radio voice communication .With transmission to a remote station PLURAL RADAR TRANSMITTING INTELLIGENCE RETURN SIGNAL CONTROLS EXTERNAL DEVICE .Missile or spacecraft guidance .Aircraft guidance .With map matching
25 R 25 A 25 B 25 C 25 D 25 E 25 F	Mapping or imaging using synthetic aperture radar (EPO)Specially adapted for moving target detection (EPO)Combined with monopulse or interferometric (EPO)With frequency domain processing of the SAR signals in azimuth (EPO)With time domain processing of the SAR signals in azimuth, e.g. time focusing (EPO)Particular SAR processing techniques (e.g., squint mode, doppler beam-sharpening mode, spotlight mode, bistatic SAR, inverse SAR) (EPO) RADAR FOR METEOROLOGICAL USE	49 50 51 52 53 54 55 56 57 58 59 60 61 62 63	With automatic lock-onWith VOR/TACAN .With Telemetry .Radar transponder only COMBINED WITH DIVERSE TYPE RADIANT ENERGY SYSTEM .With infrared device .With laser .With television .With direction finding .With radio voice communication .With transmission to a remote station PLURAL RADAR TRANSMITTING INTELLIGENCE RETURN SIGNAL CONTROLS EXTERNAL DEVICE .Missile or spacecraft guidance .Aircraft guidance

342 - 2 CLASS 342 COMMUNICATIONS: DIRECTIVE RADIO WAVE SYSTEMS AND DEVICES (E.G., RADAR, RADIO NAVIGATION)

67	.Gun (e.g., fire control)	107	.Combined with determining
68	.Proximity fuze		distance and direction
69	.Device actuated by presence of	108	With correlation
	land vehicle	109	.Combined with determining
70	.Radar mounted on and controls		distance
	land vehicle	110	With plural fixed range gates
71	With control of brakes or	111	With plural receiver frequency
	steering		band separation
72	With control of safety device	112	With plural frequencies
72	(e.g., air bags)	112	transmission
72		112	
73	RETURN SIGNAL CONTROLS RADAR	113	.Combined with determining
	SYSTEM		direction (i.e., bearing)
74	.Antenna control	114	.Combined with determining sense
75	Physical orientation		of motion (i.e., approaching
76	With ground tracking		or receding)
77	With signal error correction	115	.Digital
78	Conical scan	116	.With plural received frequency
79	Lobe switching		band separation
80	Monopulse	117	.With plural beams (e.g.,
81	Beam direction by phase or		"Janus")
	frequency control	118	DETERMINING DISTANCE
82	.Transmitter	119	.Miss distance indicator (MDI)
83	Signal phase or frequency other	120	.Altimeter
03	than pulse repetition	121	With additional indicator
		122	FM type
0.4	frequency (PRF)		
84	Function of doppler frequency	123	.Height finder
85	Function of distance	124	.Material level within container
86	With constant phase	125	.With remote cooperating station
87	With constant beat frequency	126	.Triangulation
88	Transmission timing (e.g., ring	127	.Phase comparison
	around)	128	.With frequency modulation
89	.Receiver	129	Plural frequencies transmitted
90	Automatic target detection	130	Plural modulation
91	Gain or threshold	131	Combined with pulse modulation
92	Automatic gain control (AGC)		(e.g., frequency agile)
93	Constant false alarm rate	132	With pulse modulation (e.g.,
	(CFAR)		"Chirp")
94	Gating	133	Combined with determining
95	Automatic range tracking		direction
96	Automatic track while scan	134	.With pulse modulation
50	(ATWS)	135	Digital (e.g., with counter)
97	With automatic lock-on	136	With plural fixed range gates
			_
98	Frequency	137	With variable pulse repetition
99	Doppler frequency tracking	400	frequency (PRF) or pulse width
100	With local oscillator control	138	With type "A" or "J" range
101	With filter control		scope
102	Phase	139	Combined with determining
103	Phase locked loop		direction
104	DETERMINING VELOCITY	140	With azimuth and elevation
105	.Other than doppler (e.g., range		determination
	rate)	141	Off boresight
106	.Combined with determining	142	With CRT display
	acceleration	143	Plural

144	PPI type	191	Mapping
145	.With correlation	192	.Spectrum analysis
146	.Combined with determining	193	Harmonic
	direction	194	.Complex signal (in phase and
147	DETERMINING DIRECTION		quadrature)
148	.Low angle processing	195	.Digital processing
149	.Monopulse	196	Fast fourier transform (FFT)
150	With common IF channel	197	With video quantizer
151	With channel equalization	198	.For receiver protection
152	With quadrature difference processing	199	.Automatic frequency control (AFC)
153	With particular antenna or	200	.For frequency modulation
	waveguide	201	Combined with pulse modulation
154	Combined with beam steering	202	.For pulse modulation
155	.Lobe switching	203	With noise reduction
156	.Interferometer	204	With pulse shaping
157	.With frequency or phase steering	205	.Sensitivity time control (STC)
158	.Scanning	350	DIRECTIVE
159	CLUTTER ELIMINATION	351	.Including a radiometer
160	.MTI (Moving target indicator)	352	.Including a satellite
161	With vehicle movement	353	Having a signal repeater
	compensation (e.g., AMTI	354	With beam steering
	(Airborn MTI))	355	With control of satellite
162	Digital		attitude
163	With blind speed elimination	356	Synchronous satellite
164	With storage tube	357.2	With position, velocity, or
165	TESTING OR CALIBRATING OF RADAR		attitude determination (IPC)
	SYSTEM	357.21	Determining a navigation
166	.Proximity fuze		solution using signals
167	.With laser		transmitted by a satellite
168	.With noise generation		radio beacon positioning
168 169	.With noise generation .By simulation	257 22	radio beacon positioning system
168 169 170	.With noise generation .By simulationMicrowave	357.22	<pre>radio beacon positioning systemSatellite radio beacon</pre>
168 169 170 171	.With noise generation .By simulationMicrowaveDoppler	357.22	<pre>radio beacon positioning systemSatellite radio beacon positioning system</pre>
168 169 170 171 172	.With noise generation .By simulationMicrowaveDopplerWith delay	357.22	<pre>radio beacon positioning systemSatellite radio beacon positioning system transmitting time-stamped</pre>
168 169 170 171 172 173	.With noise generation .By simulation .MicrowaveDopplerWith delay .By monitoring	357.22	<pre>radio beacon positioning systemSatellite radio beacon positioning system transmitting time-stamped messages; e.g., GPS [Global</pre>
168 169 170 171 172 173	.With noise generation .By simulation .MicrowaveDopplerWith delay .By monitoringCalibrating	357.22	radio beacon positioning systemSatellite radio beacon positioning system transmitting time-stamped messages; e.g., GPS [Global Positioning System], GLONASS
168 169 170 171 172 173 174	.With noise generation .By simulation .Microwave .Doppler .With delay .By monitoring .Calibrating WITH PARTICULAR CIRCUIT	357.22	<pre>radio beacon positioning systemSatellite radio beacon positioning system transmitting time-stamped messages; e.g., GPS [Global</pre>
168 169 170 171 172 173 174 175	.With noise generation .By simulationMicrowaveDopplerWith delay .By monitoringCalibrating WITH PARTICULAR CIRCUIT .Display	357.22	radio beacon positioning systemSatellite radio beacon positioning system transmitting time-stamped messages; e.g., GPS [Global Positioning System], GLONASS [Global Orbiting Navigation
168 169 170 171 172 173 174 175 176	.With noise generation .By simulationMicrowaveDopplerWith delay .By monitoringCalibrating WITH PARTICULAR CIRCUIT .DisplayPlural	357.22 357.23	radio beacon positioning systemSatellite radio beacon positioning system transmitting time-stamped messages; e.g., GPS [Global Positioning System], GLONASS [Global Orbiting Navigation Satellite System] or GALILEO
168 169 170 171 172 173 174 175 176 177	.With noise generation .By simulationMicrowaveDopplerWith delay .By monitoringCalibrating WITH PARTICULAR CIRCUIT .DisplayPluralProjection type		radio beacon positioning systemSatellite radio beacon positioning system transmitting time-stamped messages; e.g., GPS [Global Positioning System], GLONASS [Global Orbiting Navigation Satellite System] or GALILEO (IPC)
168 169 170 171 172 173 174 175 176 177 178	.With noise generation .By simulation .Microwave .Doppler .With delay .By monitoring .Calibrating WITH PARTICULAR CIRCUIT .Display .Plural .Projection type .Image production		radio beacon positioning systemSatellite radio beacon positioning system transmitting time-stamped messages; e.g., GPS [Global Positioning System], GLONASS [Global Orbiting Navigation Satellite System] or GALILEO (IPC)Correcting position,
168 169 170 171 172 173 174 175 176 177 178 179	.With noise generation .By simulation .Microwave .Doppler .With delay .By monitoring .Calibrating WITH PARTICULAR CIRCUIT .Display .Plural .Projection type .Image production .Stereoscopic or tridimensional	357.23	radio beacon positioning systemSatellite radio beacon positioning system transmitting time-stamped messages; e.g., GPS [Global Positioning System], GLONASS [Global Orbiting Navigation Satellite System] or GALILEO (IPC)Correcting position, velocity, or attitude
168 169 170 171 172 173 174 175 176 177 178 179 180 181	.With noise generation .By simulation .Microwave .Doppler .With delay .By monitoring .Calibrating WITH PARTICULAR CIRCUIT .Display .Plural .Projection type .Image production .Stereoscopic or tridimensional .Color	357.23	radio beacon positioning systemSatellite radio beacon positioning system transmitting time-stamped messages; e.g., GPS [Global Positioning System], GLONASS [Global Orbiting Navigation Satellite System] or GALILEO (IPC)Correcting position, velocity, or attitudeDifferential correction; e.g., DGPS [differential GPS] (IPC)
168 169 170 171 172 173 174 175 176 177 178 179 180 181	.With noise generation .By simulationMicrowaveDopplerWith delay .By monitoringCalibrating WITH PARTICULAR CIRCUIT .DisplayPluralProjection typeImage productionStereoscopic or tridimensionalColorElectronic marker generation	357.23	radio beacon positioning systemSatellite radio beacon positioning system transmitting time-stamped messages; e.g., GPS [Global Positioning System], GLONASS [Global Orbiting Navigation Satellite System] or GALILEO (IPC)Correcting position, velocity, or attitudeDifferential correction; e.g., DGPS [differential GPS]
168 169 170 171 172 173 174 175 176 177 178 179 180 181 182 183	.With noise generation .By simulationMicrowaveDopplerWith delay .By monitoringCalibrating WITH PARTICULAR CIRCUIT .DisplayPluralProjection typeImage productionStereoscopic or tridimensionalColorElectronic marker generationCursor	357.23 357.24	radio beacon positioning systemSatellite radio beacon positioning system transmitting time-stamped messages; e.g., GPS [Global Positioning System], GLONASS [Global Orbiting Navigation Satellite System] or GALILEO (IPC)Correcting position, velocity, or attitudeDifferential correction; e.g., DGPS [differential GPS] (IPC)
168 169 170 171 172 173 174 175 176 177 178 179 180 181 182 183 184	.With noise generation .By simulationMicrowaveDopplerWith delay .By monitoringCalibrating WITH PARTICULAR CIRCUIT .DisplayPluralProjection typeImage productionStereoscopic or tridimensionalColorElectronic marker generationCursorWith stabilization (e.g., True Motion, True North)	357.23 357.24 357.25	radio beacon positioning systemSatellite radio beacon positioning system transmitting time-stamped messages; e.g., GPS [Global Positioning System], GLONASS [Global Orbiting Navigation Satellite System] or GALILEO (IPC)Correcting position, velocity, or attitudeDifferential correction; e.g., DGPS [differential GPS] (IPC)Determining position (IPC)
168 169 170 171 172 173 174 175 176 177 178 179 180 181 182 183 184	.With noise generation .By simulation .Microwave .Doppler .With delay .By monitoring .Calibrating WITH PARTICULAR CIRCUIT .Display .Plural .Projection type .Image production .Stereoscopic or tridimensional .Color .Electronic marker generationCursor .With stabilization (e.g., True Motion, True North)Scan conversion	357.23 357.24 357.25	radio beacon positioning systemSatellite radio beacon positioning system transmitting time-stamped messages; e.g., GPS [Global Positioning System], GLONASS [Global Orbiting Navigation Satellite System] or GALILEO (IPC)Correcting position, velocity, or attitudeDifferential correction; e.g., DGPS [differential GPS] (IPC)Determining position (IPC)Using carrier phase measurements; e.g., kinematic positioning; using long or short baseline interferometry
168 169 170 171 172 173 174 175 176 177 178 179 180 181 182 183 184	.With noise generation .By simulation .Microwave .Doppler .With delay .By monitoring .Calibrating WITH PARTICULAR CIRCUIT .Display .Plural .Projection type .Image production .Stereoscopic or tridimensional .Color .Electronic marker generationCursor .With stabilization (e.g., True Motion, True North) .Scan conversion .With sweep expansion	357.23 357.24 357.25	radio beacon positioning systemSatellite radio beacon positioning system transmitting time-stamped messages; e.g., GPS [Global Positioning System], GLONASS [Global Orbiting Navigation Satellite System] or GALILEO (IPC)Correcting position, velocity, or attitudeDifferential correction; e.g., DGPS [differential GPS] (IPC)Determining position (IPC)Using carrier phase measurements; e.g., kinematic positioning; using long or
168 169 170 171 172 173 174 175 176 177 178 179 180 181 182 183 184	.With noise generation .By simulation .Microwave .Doppler .With delay .By monitoring .Calibrating WITH PARTICULAR CIRCUIT .Display .Plural .Projection type .Image production .Stereoscopic or tridimensional .Color .Electronic marker generationCursor .With stabilization (e.g., True Motion, True North) .Scan conversion .With sweep expansion .Augmenter	357.23 357.24 357.25	radio beacon positioning systemSatellite radio beacon positioning system transmitting time-stamped messages; e.g., GPS [Global Positioning System], GLONASS [Global Orbiting Navigation Satellite System] or GALILEO (IPC)Correcting position, velocity, or attitudeDifferential correction; e.g., DGPS [differential GPS] (IPC)Determining position (IPC)Using carrier phase measurements; e.g., kinematic positioning; using long or short baseline interferometry
168 169 170 171 172 173 174 175 176 177 178 179 180 181 182 183 184	.With noise generation .By simulation .Microwave .Doppler .With delay .By monitoring .Calibrating WITH PARTICULAR CIRCUIT .Display .Plural .Projection type .Image production .Stereoscopic or tridimensional .Color .Electronic marker generationCursor .With stabilization (e.g., True Motion, True North) .Scan conversion .With sweep expansion .Augmenter .With polarization	357.23 357.24 357.25	radio beacon positioning systemSatellite radio beacon positioning system transmitting time-stamped messages; e.g., GPS [Global Positioning System], GLONASS [Global Orbiting Navigation Satellite System] or GALILEO (IPC)Correcting position, velocity, or attitudeDifferential correction; e.g., DGPS [differential GPS] (IPC)Determining position (IPC)Using carrier phase measurements; e.g., kinematic positioning; using long or short baseline interferometry
168 169 170 171 172 173 174 175 176 177 178 179 180 181 182 183 184	.With noise generation .By simulation .Microwave .Doppler .With delay .By monitoring .Calibrating WITH PARTICULAR CIRCUIT .Display .Plural .Projection type .Image production .Stereoscopic or tridimensional .Color .Electronic marker generationCursor .With stabilization (e.g., True Motion, True North) .Scan conversion .With sweep expansion .Augmenter	357.23 357.24 357.25	radio beacon positioning systemSatellite radio beacon positioning system transmitting time-stamped messages; e.g., GPS [Global Positioning System], GLONASS [Global Orbiting Navigation Satellite System] or GALILEO (IPC)Correcting position, velocity, or attitudeDifferential correction; e.g., DGPS [differential GPS] (IPC)Determining position (IPC)Using carrier phase measurements; e.g., kinematic positioning; using long or short baseline interferometry

342 - 4 CLASS 342 COMMUNICATIONS: DIRECTIVE RADIO WAVE SYSTEMS AND DEVICES (E.G., RADAR, RADIO NAVIGATION)

	<pre>Carrier phase ambiguity resolution; floating ambiguity; LAMBDA [Least- squares AMBiguity Declaration Adjustment] method (IPC)</pre>	357.4	Cooperating elements; interaction or communication between different cooperating elements or between cooperating elements and
357.28	By combining measurements		receivers (IPC)
	of signals from the satellite radio beacon positioning	357.41	<pre>Providing carrier phase data (IPC)</pre>
	system with a supplementary	357.42	Providing aiding data (IPC)
	measurement (IPC)	357.43	Employing an initial
357.29	<pre>The supplementary measurement being of a radio- wave signal type (IPC)</pre>		estimate of the location of the receiver as aiding data or in generating aiding data
357.3	The supplementary		(IPC)
	measurement being an inertial measurement; e.g., tightly	357.44	Providing data for correcting measured
357.31	coupled inertial (IPC)By combining or switching		<pre>positioning data; e.g., DGPS [differential GPS] or</pre>
	between position solutions		ionosphere corrections (IPC)
	derived from the satellite radio beacon positioning system and position solutions	357.45	<pre>Providing integrity information; e.g., health of satellites or quality of</pre>
	derived from a further system		ephemeris data (IPC)
257 22	(IPC)	357.46	5 F 1 1 1 2 F
357.32	Whereby the further system is an inertial position		capability normally carried
	system; e.g., loosely coupled	357.47	out by the receiver (IPC)Providing dedicated
	(IPC)	357.47	supplementary positioning
357.33	Whereby the position		signals (IPC)
	solution is constrained to lie	357.48	Wherein the cooperating
	upon a particular curve or		elements are pseudolites or
	surface; e.g., for locomotives		satellite radio beacon
	on railway tracks (IPC)		positioning system signal
357.34	Relative positioning (IPC)		repeaters (IPC)
357.35	Determining velocity (IPC)	357.49	Wherein the cooperating
357.36 357.37	Determining attitude (IPC)Using carrier phase		elements are telecommunication base stations (IPC)
	measurements; using long or	357.51	Receivers (IPC)
	short baseline interferometry (IPC)	357.52	<pre>Specially adapted for specific applications (IPC)</pre>
357.38	Carrier phase ambiguity	357.53	Aircraft landing systems
	resolution; floating		(IPC)
	ambiguity; LAMBDA [Least-	357.54	Anti-theft; abduction (IPC)
	squares AMBiguity Declaration Adjustment] method)	357.55	Emergency applications (IPC)
357.39	Satellite radio beacon	357.56	Military applications (IPC)
	positioning system	357.57	Sporting applications (IPC)
	transmitting time-stamped	357.58	Integrity monitoring, fault
	messages; e.g. GPS [Global		detection or fault isolation
	Positioning System], GLONASS		of space segment)
	[Global Orbiting Navigation	357.59	Interference-related issues
	Satellite System] or GALILEO (IPC)		(IPC)
357 395	Details of the space or	357.61	Multipath-related issues
55,.555	ground control segments (IPC)		(IPC)
	5		

357.62	Testing, monitoring, correcting or calibrating of a	367	.Including directive communication system
	receiver element (IPC)	368	.Including a steerable array
357.63	Acquisition or tracking of	369	Injection radiation type
	signals transmitted by the	370	Retrodirective
	system (IPC)	371	With electronic scanning
357.64	Involving aiding data	372	Controlled
	received from a cooperating	373	With a matrix
	element; e.g., assisted GPS	374	With a switch
	(IPC)	374	
357.65	Involving a sensor	3/3	<pre>With a delay line (e.g., serpentine transmission line,</pre>
	measurement for aiding		-
	acquisition or tracking (IPC)	276	frequency scanning)
357.66	Creating, predicting or	376	Including a remote energy
337,00	correcting ephemeris or	200	source
	almanac data within the	377	Including a computer
	receiver (IPC)	378	.Utilizing correlation techniques
357.67	Satellite selection (IPC)	379	Side lobe elimination
357.68	Carrier related (IPC)	380	Sum of each antenna channel
357.69	Code related (IPC)		signal
357.71	Acquisition or tracking of	381	Difference of each antenna
337.71	other signals for positioning		channel signal
	(IPC)	382	Mixing each antenna channel signal
357.72	Multimode operation in a	383	Sum of each antenna signal
	single same satellite system;	384	Difference of each antenna
	e.g., GPS L1/L2 (IPC)	204	channel signal
357.73	Multimode operation in	385	.Beacon or receiver
	different systems which	386	With transmisson of bearing or
	transmit time-stamped	300	position determinative signals
	messages; e.g., GPS/GLONASS	207	
	(IPC)	387	Iso-chronic type
357.74	Power consumption	388	Loran
357.75	Constructional details or	389	Loran-C
	hardware or software details	390	With cycle selection
	of the signal processing chain	391	Loran-A
	(IPC)	392	With automatic gain control
357.76	Relating to the receiver	393	Iso-frequency type
	frond end (IPC)	394	Iso-phase type
357.77	Hardware or software	395	With hetrodyne
	details of the signal		synchronization
	processing chain (IPC)	396	Omega
357.78	Using Doppler frequency shift	397	Decca
358	With satellite signal	398	Rotating beacon signal
	correction	399	Tacan
359	.Including antenna orientation	400	Receiver only
360	.Including antenna pattern	401	VOR
	plotting	402	Doppler
361	.Including polarized signal	403	With circular array of
	communication transmitter or		antennas
	receiver	404	VOR
362	Receiver only	405	Doppler
363	Circular	406	With circular array of
364	Eliptical		antennas
365	Circular	407	Fixed course or bearing
366	Eliptical	,	indicating
500	· · · · · · · · · · · · · · · · · · ·		111410401119

CLASS 342 COMMUNICATIONS: DIRECTIVE RADIO WAVE SYSTEMS AND 342 - 6 DEVICES (E.G., RADAR, RADIO NAVIGATION)

408	Moving beam
409	With superimposed images
410	Glide slope transmitter or receiver
411	Receiver only
412	Transmitter only
413	Localizer transmitter or
413	receiver
414	Distinctive frequencies equi-
415	signal type
415	<pre>Coded equi-signal (e.g., A and N type)</pre>
416	Sequentially effective
	reflectors
417	Direction-finding receiver only
418	Doppler
419	Portable
420	With error or deviatioan
120	compensator or eliminator
421	Pulse-type noise elimination
121	or compensation (e.g., sky
	waves)
422	With self-orienting antenna
	pattern
423	Plural antennas
424	Tracking interferometer
425	Conical scan antenna type
426	Step track antenna type
427	Monopulse or pseuodo
	<pre>monopulse tracking antenna type</pre>
428	With continuously movable
120	antenna pattern
429	Including a stationary
123	antenna
430	Including plural moving
130	antennas
431	Including a goniometer
432	With plural fixed antenna
132	pattern comparing
433	Successively commutated
434	Including more than two
131	antennas
435	By diode switching
436	By modulation
437	Including more than two
15 /	antennas
438	Including separate indicators
439	Including combined effect
100	indicator
440	Including a goniometer
441	Having a goniometer
442	Having a phase detector
443	Having a direction indicator
444	Having plural receivers

445 ... Having more than two antennas 446 Unequal distance between at least three antennas 447 ... Having a spiral antennas ... Having a coil or loop type 448 antenna 449 ... Having a moving antenna 450 .Position indicating (e.g., triangulation) ..By computer 451 452 .. By plotting table 453 .. By deflected or repeated signal 454 ..Traffic 455 ... Having collision avoidance 456 ... Having traffic control 457 ..Land vehicle location (e.g., bus, police car 458 ..Distance 459 ..Underground object location 460 ..Storm or atomic explosion location ..With speed determination 461 462 ..With altitude determination 463 .. Having plural transmitters or receivers

FOREIGN ART COLLECTIONS

464

465

FOR 000 CLASS-RELATED FOREIGN DOCUMENTS

...Plural transmitters only

...Plural receivers only

Any foreign patents or non-patent literature from subclasses that have been reclassified have been transferred directly to FOR Collections listed below. These Collections contain ONLY foreign patents or non-patent literature. The parenthetical references in the Collection titles refer to the abolished subclasses from which these Collections were derived.