EUROPEAN PATENT OFFICE U.S. PATENT AND TRADEMARK OFFICE

CPC NOTICE OF CHANGES 1360

DATE: JANUARY1, 2023

PROJECT DP11661

The following classification changes will be effected by this Notice of Changes:

<u>Action</u>	Subclass	Group(s)
DEFINITIONS:		
Definitions Modified:	B25J	1/00, 1/02, 1/04, 1/12
	B25J	3/02, 3/04
	B25J	5/005, 5/007, 5/02
	B25J	7/00
	B25J	9/0003, 9/0012, 9/0081, 9/0084, 9/0093, 9/0096, 9/023, 9/026, 9/041, 9/042, 9/045, 9/046, 9/047, 9/06, 9/101, 9/1025, 9/103, 9/1035, 9/104, 9/1045, 9/1065, 9/107, 9/1075, 9/1085, 9/109, 9/1095, 9/123, 9/126, 9/1682
	B25J	13/003, 13/06
	B25J	15/0023, 15/04, 15/0491, 15/0616, 15/12
	B25J	17/0216, 17/0266
	B25J	18/025, 18/06
	B25J	19/0004, 19/0008, 19/0012, 19/0016, 19/002, 19/0025, 19/0029, 19/005, 19/0054, 19/0075, 19/0079, 19/0091, 19/061

No other subclasses/groups are impacted by this Notice of Changes.

This Notice of Changes includes the following [Check the ones included]:

1. CL/	ASSIF	ICATION SCHEME CHANGES
		A. New, Modified or Deleted Group(s)
		B. New, Modified or Deleted Warning(s)
		C. New, Modified or Deleted Note(s)
		D. New, Modified or Deleted Guidance Heading(s)
2. DEF	FINIT	IONS
	\boxtimes	A. New or Modified Definitions (Full definition template)
		B. Modified or Deleted Definitions (Definitions Quick Fix)
3. 🗌	REV	ISION CONCORDANCE LIST (RCL)
4.	CHA	ANGES TO THE CPC-TO-IPC CONCORDANCE LIST (CICL)
5.	CHA	ANGES TO THE CROSS-REFERENCE LIST (CRL)

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2. A. DEFINITIONS (modified)

B25J 1/00

References

Delete: The entire Informative references section.

B25J 1/02

Definition statement

Replace: The text "B25J 1/02" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "US 5647622".

References

Delete: The entire Informative references section.

B25J 1/04

Definition statement

Replace: The text "B25J 1/04" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "US 2010102583".

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References

Informative references

Attention is drawn to the following places, which may be of interest for search:

Replace: The existing Informative references text and table with the following updated table.

Devices for picking apples or like fruits	A01D46/24
Reaching devices in a shop	A47F13/06
Pliers; Other hand-held gripping tools with jaws on pivoted	B25B7/00
limbs	
Hand-held gripping tools other than those covered by group	B25B9/00
B25B7/00	
Hand implements for removing undesirable matter, e.g. litter	E01H1/12
pickers	

B25J 1/12

Definition statement

Delete: The text "DE 102008013729" from the Definition statement

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B25J 3/02

Definition statement

Replace: The existing Definition statement text with the following updated text.

Master-slave manipulators having a mechanical connection between the master unit and the slave unit (e.g. connection by shafts, rods, wires, etc).

Illustrative example of subject matter classified in this group:

Delete: The text "WO 9718927".

References

Delete: The entire Informative references section.

B25J 3/04

Definition statement

Replace: The existing Definition statement text with the following updated text.

Master-slave manipulators having an electrical connection between the master unit and the slave unit (i.e. the movements of the master unit are transformed into electrical signals for controlling actuators of the slave unit).

Illustrative example of subject matter classified in this group:

Delete: The text "US 6197017".

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References

Informative references

<u>Delete</u>: The following text and table from the Informative references section.

Attention is drawn to the following Fterms (Japanese classification scheme), which may be of interest for search:

Control bars electrically connected to slave parts	3C007/JT04
Having reaction force sensing functions	3C007JT05
Correspondence relationships between main parts and slave	3C007JT06
parts changeable	
Having additional setting functions	3C007/JT07
Providing manipulators per se as control bars	3C007/JT09
Realization or copying human motions	3C007/JT10

B25J 5/005

Definition statement

Replace: The text "B25J 5/005" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "US 2009095096".

References

Informative references

<u>Delete</u>: The following text and table from the Informative references section.

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Attention is drawn to the following Fterms (Japanese classification scheme), which may be of interest for search:

Crawlers	3C007/WA17
I CIAWICIS	1 30001/ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \

B25J 5/007

Definition statement

Replace: The text "B25J 5/007" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "EP 0008981".

References

Informative references

Delete: The following text and table from the Informative references section.

Attention is drawn to the following Fterms (Japanese classification scheme), which may be of interest for search:

Wheel-type autonomous robots	3C007/WA16
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B25J 5/02

Definition statement

Replace: The text "B25J 5/02" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

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Delete: The text "EP 0705665".

References

Delete: The entire Informative references section.

B25J 7/00

Definition statement

Replace: The existing Definition statement text with the following updated text.

Manipulators performing tasks at a level of precision that can usually not be achieved by the unaided human hand.

Illustrative example of subject matter classified in this group:

Delete: The text "EP 0906813".

References

Informative references

Delete: The following text and table from the Informative references section.

Micromanipulators	3C007/BS30
Structure / purpose of micromanipulators	3C007/XG00

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B25J 9/0003

Definition statement

Replace: The existing Definition statement text with the following updated text.

Robots which operates semi- or fully autonomously to perform services useful to the well-being of humans and equipment, excluding manufacturing operations.

Illustrative example of subject matter classified in this group:

Delete: The text "US 2005091684".

References

Informative references

Delete: The following text and table from the Informative references section.

Attention is drawn to the following Fterms (Japanese classification scheme), which may be of interest for search:

Robots for service	3C007/AS34
Robots for medical treatment	3C007/AS35
Robots for entertainment	3C007/AS36

B25J 9/0012

Definition statement

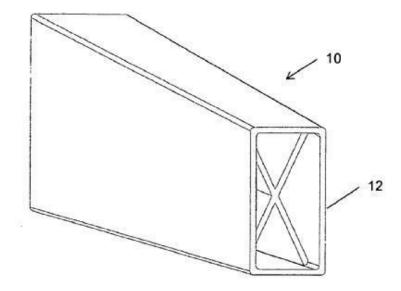
Replace: The text "B25J 9/0012" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

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Delete: The text "US 2010304097".



Insert: The following new text beneath the image in the Definition statement.

This group relates to, but is not limited to, providing a design solution that overcomes the heavy weight of robot structures that are expected to handle heavy payloads with high speeds through complex spatial trajectories at a long reach while preserving high positional accuracy and dynamic performance, by applying composite materials to robot structures.

References

Delete: The entire Informative references section.

Glossary of terms

In this place, the following terms or expressions are used with the meaning indicated:

<u>Replace</u>: The term "artifical" with the corrected spelling "artificial" in the Glossary of terms table.

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Synthetic	Man-made materials made of artificial chemicals as
materials	opposed to organic ones. They include plastics (polythene,
	polystyrene), synthetic fibres (nylon, acrylics, polyesters),
	synthetic resins and synthetic rubber

B25J 9/0081

Definition statement

Replace: The text "B25J 9/0081" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "US 4283764".

References

Informative references

<u>Delete</u>: The following text and table from the Informative references section.

Attention is drawn to the following Fterms (Japanese classification scheme), which may be of interest for search:

Teaching auxiliary tool	3C007/JU07
Mount hand	3C007/JU08
Teaching by man power	3C007/LS02

Glossary of terms

In this place, the following terms or expressions are used with the meaning indicated:

Replace: The term "master" with "Master" in the Glossary of terms table.

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Master teach-in	Devices manually moved in space by an operator for
means	teaching the path of a manipulator.

B25J 9/0084

Definition statement

Replace: The existing Definition statement text with the following updated text.

Both robotic installation comprising several manipulators and manipulators comprising two arms connected to a single basis.

Illustrative example of subject matter classified in this group:

Delete: The text "FR 2874190".

References

Informative references

Delete: The entire Informative references section.

B25J 9/0093

Definition statement

Replace: The text "B25J 9/0093" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "EP 0512126".

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References

Informative references

<u>Delete</u>: The following text and table from the Informative references section.

Attention is drawn to the following Fterms (Japanese classification scheme), which may be of interest for search:

Work object movable b	y conveyor	3C007/NS02

B25J 9/0096

Definition statement

Replace: The text "B25J 9/0096" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "WO 9104522".

References

Informative references

Delete: The entire Informative references section.

B25J 9/023

Definition statement

Replace: The existing Definition statement text with the following updated text.

Manipulators consisting of prismatic joints connected in series and allowing movements along perpendicular axis.

Illustrative example of subject matter classified in this group:

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Delete: The text "US 6264419".

References

Informative references

<u>Delete</u>: The following text and table from the Informative references section.

Attention is drawn to the following Fterms (Japanese classification scheme), which may be of interest for search:

Cartesian coordinates robots with two degrees of freedom	3C007/BS02
Cartesian coordinates robots with three degrees of freedom	3C007/BS03

B25J 9/026

Definition statement

Replace: The existing Definition statement text with the following updated text.

Cartesian coordinate type manipulators having three prismatic joints, wherein one joint is formed by a carriage running on an overhead horizontal beam supported at its two ends by other beams.

Illustrative example of subject matter classified in this group:

Delete: The text "GB179322".

References

Informative references

Delete: The following text and table from the Informative references section.

Gantry type robots	3C007/BS05
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B25J 9/041

Definition statement

Replace: The existing Definition statement text with the following updated text.

Manipulators having a kinematic chain including at least a revolute joint and arranged so that the working envelope of the manipulator is a cylinder. The kinematic chain usually includes a revolute joint having a vertical axis and two prismatic joints having respectively a vertical and a horizontal axis.

Illustrative example of subject matter classified in this group:

Delete: The text "US4642212".

References

Delete: The entire Informative references section.

B25J 9/042

Definition statement

Delete: The text "EP 1671755".

References

Informative references

Delete: The entire Informative references section.

B25J 9/045

Definition statement

Replace: The existing Definition statement text with the following updated text.

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Manipulators having a kinematic chain comprising two revolute joints and a prismatic joint arranged so that the working envelope of the manipulator is a part of a sphere.

Illustrative example of subject matter classified in this group:

Delete: The text "US3784031".

References

Informative references

Delete: The entire Informative references section.

B25J 9/046

Definition statement

Replace: The existing Definition statement text with the following updated text.

Manipulators having a kinematic chain including at least two subsequent revolute joints having parallel horizontal axis.

The most common revolute coordinate type manipulators have six revolute joints: a first joint having a vertical axis between a basis and a carrousel, a second joint between the carrousel and a lower arm, a third joint between the lower arm and an upper arm, the second and third joint shaving parallel horizontal axis and three further joints for the wrist.

Illustrative example of subject matter classified in this group:

Delete: The text "DE 3939836".

References

Informative references

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B25J 9/047

Definition statement

Replace: The existing Definition statement text with the following updated text.

Revolute coordinate type manipulators having the axis of the second revolute joint between the carrousel and the lower arm being offset from the vertical axis of the first revolute joint between the basis and the carrousel.

Illustrative example of subject matter classified in this group:

Delete: The text "DE 29711523 U".

References

Informative references

Delete: The entire Informative references section.

B25J 9/06

Definition statement

Replace: The existing Definition statement text with the following updated text.

Manipulator arms having multiple articulations placed in series.

Illustrative example of subject matter classified in this group:

Delete: The text "EP0136719".

References

Informative references

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B25J 9/101

Definition statement

Replace: The text "B25J 9/101" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "US 20100178101".

References

Informative references

<u>Delete</u>: The following text and table from the Informative references section.

Attention is drawn to the following Fterms (Japanese classification scheme), which may be of interest for search:

Butting and stopping	3C007/CY13

B25J 9/1025

Definition statement

Replace: The text "B25J 9/101" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "US 4518308".

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References

Informative references

Delete: The entire Informative references section.

Special rules of classification

<u>Replace</u>: The existing text in the Special rules of classification section with the following updated text.

Harmonic drives consist of three basic parts:

- the circular spline which is a rigid ring with internal teeth, engaging the teeth of the flexspine across the major axis of the wave generator;
- the flexspine which is a non-rigid, thin cylindrical cup with external teeth on a slightly smaller pitch diameter than the circular spline; it fits over and is held in an elliptical shape by the wave generator; and
- the wave generator which is a thin, raced ball bearing fitted onto an elliptical plug serving as a high efficiency torque converter.

The advantages include: no backlash, compactness and light weight, high gear ratios and high torque capability.

B25J 9/103

Definition statement

Replace: The text "B25J 9/103" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "JP 63023064".

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References

Informative references

<u>Delete</u>: The following text and table from the Informative references section.

Attention is drawn to the following Fterms (Japanese classification scheme), which may be of interest for search:

Back lash prevention	3C007/HT31

B25J 9/1035

Definition statement

Replace: The text "B25J 9/103" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "EP 0218075".

References

Informative references

Delete: The following text and table from the Informative references section.

Rack and pinion	3C007/HT22
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B25J 9/104

Definition statement

Replace: The text "B25J 9/104" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "EP 0076947".

References

Informative references

<u>Delete</u>: The following text and table from the Informative references section.

Attention is drawn to the following Fterms (Japanese classification scheme), which may be of interest for search:

Flexible transmission member	3C007/HT01
Belt	3C007/HT02
Chain	3C007/HT03
Rope / Wire	3C007/HT04

B25J 9/1045

Definition statement

Replace: The text "B25J 9/1045" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "US 2002148320".

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References

Informative references

Delete: The entire Informative references section.

B25J 9/1065

Definition statement

Replace: The text "B25J 9/1065" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "EP 0396752".

References

Informative references

Delete: The entire Informative references section.

B25J 9/107

Definition statement

Replace: The text "B25J 9/107" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "WO 2010143505".

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References

Informative references

<u>Delete</u>: The following text and table from the Informative references section.

Attention is drawn to the following Fterms (Japanese classification scheme), which may be of interest for search:

Frog-leg type	3C007/BS23
Pantograph mechanisms	5F031/GA44

B25J 9/1075

Definition statement

Replace: The text "B25J 9/1075" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "US 2005121929".

References

Informative references

Delete: The following text and table from the Informative references section.

Artificial muscles	3C007/HS21
Type of actuators; Elastic shrink-tubes or rubber bags	3H081/AA18

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Glossary of terms

In this place, the following terms or expressions are used with the meaning indicated:

Replace: The term "coponent" with the corrected spelling "component" in the Glossary of terms table.

Replace: The term "reversiby" with the corrected spelling "reversibly" in the Glossary of terms table.

Artificial	rtificial Generic term used for materials or devices that can	
muscle	reversibly contract, expand, or rotate within one component	
due to an external stimulus (such as voltage, curre		
	pressure or temperature). Conventional motors and	
pneumatic linear or rotary actuators do not qualify as		
artificial muscles because there is more than one		
component involved in the actuation.		

B25J 9/1085

Definition statement

Replace: The text "B25J 9/1085" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "US 4932210".

References

Informative references

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B25J 9/109

Definition statement

Replace: The text "B25J 9/109" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "DE 2742103".

References

Informative references

Delete: The entire Informative references section.

Glossary of terms

In this place, the following terms or expressions are used with the meaning indicated:

Delete: The phrase "allow to" from the Glossary of terms table.

Mechanical	Mechanical parts having a specific shape which create a
programming	periodic movement so that the manipulator can execute a
means	predetermined sequence of operations in a synchronized
	way.

B25J 9/1095

Definition statement

Replace: The existing Definition statement text with the following updated text.

Manipulators provided with an actuator directly powered by a chemical reaction or comprising a chemically synthesized material (e.g. a polymer) able to produce mechanical energy when stimulated (e.g. by an electric current).

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Illustrative example of subject matter classified in this group:

Delete: The text "US 2008169729".

References

Informative references

Delete: The following text and table from the Informative references section.

Attention is drawn to the following Fterms (Japanese classification scheme), which may be of interest for search:

Mechano-chemical actuator	3C007/HS07
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B25J 9/123

Definition statement

Replace: The text "B25J 9/123" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "DE 102006016195".

References

Informative references

Delete: The following text and table from the Informative references section.

Linear motors	3C007/HS26
Linear motors	30007/11320

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B25J 9/126

Definition statement

Replace: The text "B25J 9/126" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "FR 2617751".

References

Informative references

Delete: The entire Informative references section.

B25J 9/1682

Definition statement

Replace: The text "B25J 9/1682" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "EP 0607619".

References

Informative references

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B25J 13/003

Definition statement

Replace: The text "B25J 13/003" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "DE 3327808".

References

Informative references

Delete: The following text and table from the Informative references section.

Attention is drawn to the following Fterms (Japanese classification scheme), which may be of interest for search:

Control of robot by voice input	3C007/WB19

B25J 13/06

Definition statement

Replace: The text "B25J 13/06" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "EP1405700".

References

Informative references

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B25J 15/0023

Definition statement

Replace: The text "B25J 15/0023" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "SU 1047680".

References

Informative references

Delete: The following text and table from the Informative references section.

Attention is drawn to the following Fterms (Japanese classification scheme), which may be of interest for search:

Use of fluid pressure	3C007/EV12
Elastic membrane (with open spaces, closed spaces, filled	3C007/EV14
spaces	

B25J 15/04

Definition statement

Replace: The text "B25J 15/04" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "EP 0288744".

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References

Informative references

<u>Delete</u>: The entire Informative references section.

B25J 15/0491

Definition statement

Replace: The text "B25J 15/0491" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "EP 0120275".

References

Informative references

Delete: The entire Informative references section.

B25J 15/0616

Definition statement

Replace: The text "B25J 15/0616" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "US 2008202602".

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References

Informative references

<u>Delete</u>: The following text and table from the Informative references section.

Attention is drawn to the following Fterms (Japanese classification scheme), which may be of interest for search:

Vacuum absorption	3C007/FS01
Structure of absorption part	3C007/FT00
Purpose of absorption device	3C007/FU00

B25J 15/12

Definition statement

Replace: The text "B25J 15/12" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "DE 102004034537".

References

Informative references

Delete: The following text and table from the Informative references section.

Wholly flexible finger member	3C007/ES10
<u> </u>	

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B25J 17/0216

Definition statement

Replace: The existing Definition statement text with the following updated text.

Exclusively parallel kinematics manipulators having 6 linear actuators linked to a base and a moving platform by means of universal or ball joints and allowing 6 degrees of freedom for the platform.

Illustrative example of subject matter classified in this group:

References

Informative references

Delete: The following text and table from the Informative references section.

Attention is drawn to the following Fterms (Japanese classification scheme), which may be of interest for search:

Parallel link type manipulator	3C007/BS24

B25J 17/0266

Definition statement

Replace: The text "B25J 17/0266" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "WO 0035640".

References

Informative references

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Delete: The following text and table from the Informative references section.

Attention is drawn to the following Fterms (Japanese classification scheme), which may be of interest for search:

-		
	Parallel link type manipulator	3C007/BS24

B25J 18/025

Definition statement

Replace: The text "B25J 18/025" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "EP 0362680".

References

Informative references

Delete: The following text and table from the Informative references section.

Expandable and contractible	3C007/CU02 3C007/CV02
Telescopic type	3C007/CU23 C007/CW02

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B25J 18/06

Definition statement

Replace: The text "B25J 18/06" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "EP 2335884".

References

Informative references

Delete: The entire Informative references section.

B25J 19/0004

Definition statement

Replace: The text "B25J 19/0004" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "EP 0109252".

References

Informative references

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B25J 19/0008

References

Informative references

Delete: The entire Informative references section.

B25J 19/0012

Definition statement

Replace: The text "B25J 19/0012" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "EP 2301727".

References

Informative references

<u>Delete</u>: The entire Informative references section.

B25J 19/0016

Definition statement

Replace: The text "B25J 19/0016" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "GB 2114536".

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References

Informative references

<u>Delete</u>: The following text and table from the Informative references section.

Attention is drawn to the following Fterms (Japanese classification scheme), which may be of interest for search:

Load-balancing	by springs	3C007/CY23

B25J 19/002

Definition statement

Replace: The text "B25J 19/002" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "EP 0392926".

References

Informative references

Delete: The entire Informative references section.

B25J 19/0025

Definition statement

Replace: The text "B25J 19/0025" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "DE 20022990 U".

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References

Informative references

<u>Delete</u>: The following text and table from the Informative references section.

Attention is drawn to the following Fterms (Japanese classification scheme), which may be of interest for search:

Cable disposition along external main body surface 3C007/CY07

B25J 19/0029

Definition statement

Replace: The text "B25J 19/0029" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "EP 1852225".

References

Informative references

Delete: The entire Informative references section.

B25J 19/005

Definition statement

Replace: The text "B25J 19/005" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "EP 1526626".

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References

Informative references

Delete: The entire Informative references section.

B25J 19/0054

Definition statement

Replace: The text "B25J 19/0054" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "DE 29711523 U".

References

Informative references

Delete: The entire Informative references section.

B25J 19/0075

References

Informative references

<u>Delete</u>: The following text and table from the Informative references section.

	00007/01/00
Dust proof: provide cover	3C007/CY29

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B25J 19/0079

Definition statement

Replace: The text "B25J 19/0079" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "EP 0447881".

References

Informative references

Delete: The entire Informative references section.

B25J 19/0091

Definition statement

Replace: The text "B25J 19/0091" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "EP 0683019".

References

Informative references

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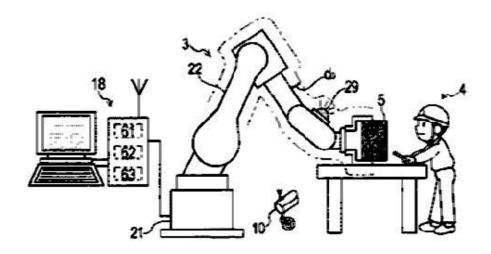
B25J 19/061

Definition statement

Replace: The text "B25J 19/061" in the Definition statement with "this group:".

Illustrative example of subject matter classified in this group:

Delete: The text "JP 2010120139".



Insert: The following text beneath the image in the Definition statement.

Robot 3 itself, or its vicinity, is equipped with alarm 29 so that it can warn for operator 4 who operates/works with robot 3.

References

Informative references