CPC COOPERATIVE PATENT CLASSIFICATION

G PHYSICS

(NOTES omitted)

INSTRUMENTS

G01 MEASURING; TESTING

(NOTES omitted)

G01P MEASURING LINEAR OR ANGULAR SPEED, ACCELERATION, DECELERATION, OR SHOCK; INDICATING PRESENCE, ABSENCE, OR DIRECTION, OF

MOVEMENT (measuring or recording blood flow A61B 5/02, A61B 8/06; monitoring speed or deceleration of electrically-propelled vehicles B60L 3/00; vehicle lighting systems adapted to indicate speed B60Q 1/54; determining position or course in navigation, measuring ground distance in geodesy or surveying G01C; combined measuring devices for measuring two or more variables of movement G01C 23/00; measuring velocity of sound G01H; measuring velocity of light G01J 7/00; measuring direction or velocity of solid objects by reception or emission of radiowaves or other waves and based on propagation effects, e.g. Doppler effect, propagation time, direction of propagation, G01S; measuring speed of nuclear radiation G01T; measuring acceleration of gravity G01V; {measuring or recording the speed of trains B61L 23/00; speed indicators incorporated in motor vehicles B60K 35/00; measuring frequency or phase G01R; traffic control G08G})

NOTES

- 1. This subclass <u>covers</u> measuring direction or velocity of flowing fluids using propagation effects of radiowaves or other waves caused in the fluid itself, e.g. by laser anemometer, by ultrasonic flowmeter with "sing-around-system".
- 2. Attention is drawn to the Notes following the title of class <u>G01</u>.

• • • {by comparing the time duration between two impulses with a reference time}

WARNING

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In this subclass non-limiting references (in the sense of paragraph 39 of the Guide to the IPC) may still be displayed in the scheme.

1/00	Details of instruments	1/11	• • • by the detection of the position of the
1/003	• {used for damping}		indicator needle
1/006	• {used for thermal compensation}	1/12	 Recording devices (indicating working conditions of
1/02	. Housings		vehicles <u>G07C 5/00</u>)
1/023	• • {for acceleration measuring devices}	1/122	• • {Speed recorders}
1/026	• • {for speed measuring devices, e.g. pulse	1/125	• • { with recording discs }
	generator}	1/127	• • {for acceleration values}
1/04	Special adaptations of driving means	1/14	• • for permanent recording {(G01P 1/125 takes
1/06	• {Indicating or recording devices, e.g. for remote		precedence)}
	indication (indicating or recording in general G01D;	1/16	for erasable recording, e.g. magnetic recording
	registering or indicating working conditions of vehicles G07C 5/00)}	3/00	Measuring linear or angular speed; Measuring
1/07	. Indicating devices, e.g. for remote indication		differences of linear or angular speeds
	(indicating working conditions of vehicles		(G01P 5/00 - G01P 11/00 take precedence; {direction and speed indication G01P 13/045}; counting
	<u>G07C 5/00</u>)		mechanisms <u>G06M</u>)
1/08	Arrangements of scales, pointers, lamps		mechanisms <u>Goolvi</u>)
	or acoustic indicators, e.g. in automobile		<u>NOTE</u>
	speedometers		The sub-groups of this group are distinguished
1/10	• • • for indicating predetermined speeds		by the method of measurement which is of major
1/103	• • • {by comparing the value of the measured		importance. Thus the mere application of other
	signal with one or several reference values		methods for giving a final indication does not
	(in general <u>G01R 17/00</u>)}		affect the classification.

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3/02	 Devices characterised by the use of mechanical means 	3/4815	• • • • {using a pulse wire sensor, e.g. Wiegand wire}
3/04	• • by comparing two speeds	3/482	• • • • delivered by nuclear radiation detectors
3/06	using a friction gear	3/483	delivered by variable capacitance detectors
3/08	using differential gearing	3/484	delivered by contact-making switches
3/10	by actuating an indicating element, e.g. pointer,	3/486	delivered by photo-electric detectors
	for a fixed time	3/487	delivered by rotating magnets
3/12	by making use of a system excited by impact	3/488	delivered by variable reluctance detectors
3/14	by exciting one or more mechanical resonance	3/489	Digital circuits therefor
	systems	3/49	using eddy currents
3/16	by using centrifugal forces of solid masses	3/495	where the indicating means responds to
	{(governors <u>G05D 13/10</u>)}	3/4/3	forces produced by the eddy currents and the
3/18	transferred to the indicator by mechanical		generating magnetic field
	means	3/4953	• • • • { with a counter for the covered distance
3/20	transferred to the indicator by fluid means	3/4/33	incorporated (measuring the covered
3/22	transferred to the indicator by electric or		distance G01C 22/00)}
3/ 22	magnetic means	3/4956	• • • • {with thermal compensation}
3/24	• by using friction effects (G01P 3/06 takes	3/4/30	• for measuring linear speed (G01P 3/56 takes
3/24	precedence)	3/30	precedence)
3/26	Devices characterised by the use of fluids	2/505	• • {by using eddy currents}
		3/505	
3/263	• • {by using fluidic impulse generators}	3/52	• • • by measuring amplitude of generated current or
3/266	• • {by using a vortex chamber}	2/54	voltage
3/28	• by using pumps	3/54	by measuring frequency of generated current or
3/30	by using centrifugal forces of fluids	2/5	voltage
3/32	in a rotary container communicating with a	3/56	for comparing two speeds
	fixed container	3/565	• • • {by measuring or by comparing the phase
3/34	by using friction effects		of generated current or voltage (phase
3/36	 Devices characterised by the use of optical means, 		comparators per se H03D 13/00; phase
	e.g. using infrared, visible, or ultraviolet light	2.50	measurement $\underline{G01R}$ $\underline{25/00}$)
	(G01P 3/68) takes precedence; gyrometers using	3/58	by measuring or comparing amplitudes of
	the Sagnac effect, i.e. rotation-induced shifts		generated currents or voltage {(amplitude
	between counter-rotating electromagnetic beams	2/60	comparators <u>H03K 5/24</u>)}
0/0/0	<u>G01C 19/64</u>)	3/60	• • • by measuring or comparing frequency of
3/363	• • {by using a ring laser (ring lasers in general		generated currents or voltages {(frequency
2/2//	<u>H01S 3/083</u>)}	2/62	comparators <u>H03K 5/26</u>)}
3/366	• • {by using diffraction of light (for measuring	3/62	 Devices characterised by the determination or the variation of atmospheric pressure with height
2/20	speed of fluids $\underline{G01P5/26}$)		to measure the vertical components of speed
3/38	• using photographic means		(measuring pressure in general G01L)
3/40	. using stroboscopic means	3/64	Devices characterised by the determination of the
3/42	• Devices characterised by the use of electric or	3/04	time taken to traverse a fixed distance
	magnetic means (G01P 3/66 takes precedence;	3/66	 using electric or magnetic means (G01P 3/80)
	measuring electric or magnetic values in general	3/00	takes precedence; measuring short time intervals
2/44	G01R)		<u>G04F 8/00, G04F 10/00</u>)
3/44	• • for measuring angular speed (G01P 3/56 takes	3/665	• • {for projectile velocity measurements}
2/442	precedence)	3/68	 using optical means, i.e. using infrared, visible, or
3/443	• • • {mounted in bearings (bearings <u>F16C</u>)}	3/00	ultraviolet light (G01P 3/80 takes precedence {;
3/446	• • • • {mounted between two axially spaced rows		by reflection of waves $GO1S 17/58$ }
2115	of rolling elements}	3/685	• • {for projectile velocity measurements}
3/46	by measuring amplitude of generated current or	3/80	 (10) projectile verocity measurements; . using auto-correlation or cross-correlation
	voltage {(in general <u>G01R 19/00</u>)}	3/80	detection means
3/465	• • • • {by using dynamo-electro tachometers or	2/902	
	electric generator}	3/803	• • {in devices of the type to be classified in
3/48	by measuring frequency of generated current or	2/906	G01P 3/66}
	voltage {(in general G01R 23/00)}	3/806	• • { in devices of the type to be classified in G01P 3/68}
3/4802	• • • {by using electronic circuits in general}		<u>GOIP 3/08</u> }
3/4805	• • • • {by using circuits for the electrical	5/00	Measuring speed of fluids, e.g. of air stream;
	integration of the generated pulses		Measuring speed of bodies relative to fluids, e.g.
	(measuring impulse frequency by		of ship, of aircraft (application of speed-measuring
2::0:=	integration G01R 23/09)}		devices for measuring volume of fluid <u>G01F</u>)
3/4807	• • • • {by using circuits for the detection of the	5/001	• {Full-field flow measurement, e.g. determining flow
	pulses delivered by the ignition system of		velocity and direction in a whole region at the same
2/401	an internal combustion engine}		time, flow visualisation}
3/481	of pulse signals	5/003	• {by measuring fluid level in front of an obstacle}

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5/005	• {by using a jet directed into the fluid}	13/0006	• {of fluids or of granulous or powder-like
5/006	 {the jet used is composed of ionised or radioactive particles} 	13/0013	substances}• {by using a solid body which is shifted by the
5/008	• {by using an electrolyte added to the fluid}	13/0013	action of the fluid}
5/01	• by using swirlflowmeter	13/002	• • { with electrical coupling to the indicating
5/02	• by measuring forces exerted by the fluid on solid	10/000	devices}
5 (0.4	bodies, e.g. anemometer	13/0026	• • {by using deflection of baffle-plates}
5/04 5/06	using deflection of baffle-platesusing rotation of vanes (measuring speed of	13/0033	• • { with electrical coupling to the indicating device }
3/00	rotating shafts G01P 3/00)	13/004	• • {by using the rotation of vanes}
5/065	• • • { with mechanical coupling to the indicating	13/0046	• • { with electrical coupling to the indicating
5/07	device} with electrical coupling to the indicating device	13/0053	<pre>device} {by using dynamo-electric effect}</pre>
5/08	 by measuring variation of an electric variable 	13/0053	 (by using dynamo-electric electry) (by using thermal variables)
3/00	directly affected by the flow, e.g. by using dynamo-	13/0066	• • {by using differences of pressure in the fluid}
	electric effect	13/0073	• • {by using vibrations generated by the fluid}
5/083	• • {by using electronic circuits for measuring the	13/008	• {by using a window mounted in the fluid carrying
5 /00 <i>c</i>	dynamoelectric effect}		tube (G01P 13/0013, G01P 13/0026, G01P 13/004
5/086	 {by using special arrangements and constructions for measuring the dynamo-electric effect} 	12/0096	take precedence)}
5/10	 by measuring thermal variables 	13/0086	 { with photo-electric detection } {by making use of products, e.g. chemical products
5/10	 by measuring thermal variables using variation of resistance of a heated conductor 	13/0093	added to the fluid in order to make the fluid flow
5/14	 by measuring differences of pressure in the fluid 		visible}
5/16	• • using Pitot tubes {, e.g. Machmeter}	13/02	. Indicating direction only, e.g. by weather vane
5/165	Arrangements or constructions of Pitot tubes	13/025	• • {indicating air data, i.e. flight variables of an
5/17	Coupling arrangements to the indicating device		aircraft, e.g. angle of attack, side slip, shear, yaw}
5/175	with the determination of Mach number (analogue computers therefor G06G 7/57)	13/04	Indicating positive or negative direction of a linear movement or clockwise or anti-clockwise
5/18	 by measuring the time taken to traverse a fixed 		direction of a rotational movement
	distance	13/045	• • { with speed indication }
5/20	 using particles entrained by a fluid stream 	15/00	Measuring acceleration; Measuring deceleration;
	(CO1D 5/22 talaa amaadana)	15/00	Measuring acceleration, Measuring deceleration,
5/22	(G01P 5/22 takes precedence) using auto-correlation or cross-correlation	15/00	Measuring shock, i.e. sudden change of acceleration
	 using auto-correlation or cross-correlation detection means 	15/001	Measuring shock, i.e. sudden change of
5/22 5/24	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming 	15/001	Measuring shock, i.e. sudden change of acceleration • {by measuring acceleration changes by making use of a triple differentiation of a displacement signal}
	 using auto-correlation or cross-correlation detection means 		Measuring shock, i.e. sudden change of acceleration • {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} • {Kinematic accelerometers, i.e. measuring}
	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. 	15/001	Measuring shock, i.e. sudden change of acceleration • {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} • {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001,
5/24 5/241	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} 	15/001 15/003	 Measuring shock, i.e. sudden change of acceleration {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)}
5/24	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or 	15/001 15/003 15/005	Measuring shock, i.e. sudden change of acceleration • {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} • {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} • • {measuring translational acceleration}
5/24 5/241	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes 	15/001 15/003 15/005 15/006	Measuring shock, i.e. sudden change of acceleration • {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} • {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} • • {measuring translational acceleration} • {by making use of fluid seismic masses}
5/24 5/241	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or 	15/001 15/003 15/005 15/006 15/008	Measuring shock, i.e. sudden change of acceleration • {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} • {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} • • {measuring translational acceleration} • {by making use of fluid seismic masses} • • {by using thermal pick-up}
5/24 5/241 5/242	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} {involving pulsed waves} {by measuring transit time of acoustical waves 	15/001 15/003 15/005 15/006	Measuring shock, i.e. sudden change of acceleration • {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} • {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} • {measuring translational acceleration} • {by making use of fluid seismic masses} • {by using thermal pick-up} • by making use of inertia forces {using solid seismic
5/241 5/241 5/242 5/244	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} {involving pulsed waves} {by measuring transit time of acoustical waves (measuring propagation velocity of acoustical 	15/001 15/003 15/005 15/006 15/008 15/02	Measuring shock, i.e. sudden change of acceleration • {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} • {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} • {measuring translational acceleration} • {by making use of fluid seismic masses} • • {by using thermal pick-up} • by making use of inertia forces {using solid seismic masses}(G01P 15/14 takes precedence)
5/241 5/242 5/242 5/244 5/245	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} {involving pulsed waves} {by measuring transit time of acoustical waves (measuring propagation velocity of acoustical waves per se G01H 5/00)} 	15/001 15/003 15/005 15/006 15/008	Measuring shock, i.e. sudden change of acceleration • {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} • {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} • {measuring translational acceleration} • {by making use of fluid seismic masses} • {by using thermal pick-up} • by making use of inertia forces {using solid seismic
5/241 5/242 5/244 5/245 5/247	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} {involving pulsed waves} {by measuring transit time of acoustical waves (measuring propagation velocity of acoustical waves per se G01H 5/00)} {Sing-around-systems} 	15/001 15/003 15/005 15/006 15/008 15/02	 Measuring shock, i.e. sudden change of acceleration {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} {measuring translational acceleration} {by making use of fluid seismic masses} {by using thermal pick-up} by making use of inertia forces {using solid seismic masses}(G01P 15/14 takes precedence) by using non-electrical means {by measuring the displacement of a movable inertial mass}
5/241 5/242 5/242 5/244 5/245	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} {involving pulsed waves} {by measuring transit time of acoustical waves (measuring propagation velocity of acoustical waves per se G01H 5/00)} {Sing-around-systems} {by measuring the direct influence of the streaming 	15/001 15/003 15/005 15/006 15/008 15/02	Measuring shock, i.e. sudden change of acceleration • {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} • {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} • • {measuring translational acceleration} • {by making use of fluid seismic masses} • • {by using thermal pick-up} • by making use of inertia forces {using solid seismic masses}(G01P 15/14 takes precedence) • • by using non-electrical means • • {by measuring the displacement of a movable}
5/241 5/242 5/244 5/245 5/247 5/248	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} {involving pulsed waves} {by measuring transit time of acoustical waves (measuring propagation velocity of acoustical waves per se G01H 5/00)} {Sing-around-systems} {by measuring phase differences} 	15/001 15/003 15/005 15/006 15/008 15/02 15/03 15/032	 Measuring shock, i.e. sudden change of acceleration {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} {measuring translational acceleration} {by making use of fluid seismic masses} {by using thermal pick-up} by making use of inertia forces {using solid seismic masses}(G01P 15/14 takes precedence) by using non-electrical means {by measuring the displacement of a movable inertial mass} {for indicating angular accelerations
5/241 5/242 5/244 5/245 5/247 5/248	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} {involving pulsed waves} {by measuring transit time of acoustical waves (measuring propagation velocity of acoustical waves per se G01H 5/00)} {Sing-around-systems} {by measuring the direct influence of the streaming 	15/001 15/003 15/005 15/006 15/008 15/02 15/03 15/032 15/034 15/036	Measuring shock, i.e. sudden change of acceleration • {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} • {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} • • {measuring translational acceleration} • {by making use of fluid seismic masses} • • {by using thermal pick-up} • by making use of inertia forces {using solid seismic masses}(G01P 15/14 takes precedence) • • by using non-electrical means • • • {by measuring the displacement of a movable inertial mass} • • • {for indicating angular accelerations (G01P 15/036 takes precedence)} • • • {for indicating predetermined acceleration values}
5/241 5/242 5/244 5/245 5/247 5/248 5/26	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} {involving pulsed waves} {by measuring transit time of acoustical waves (measuring propagation velocity of acoustical waves per se G01H 5/00)} {Sing-around-systems} {by measuring the direct influence of the streaming fluid on the properties of a detecting optical wave Measuring speed by integrating acceleration (measuring travelled distance by double integration of	15/001 15/003 15/005 15/006 15/008 15/02 15/03 15/032 15/034 15/036 15/038	Measuring shock, i.e. sudden change of acceleration • {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} • {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} • • {measuring translational acceleration} • {by making use of fluid seismic masses} • • {by using thermal pick-up} • by making use of inertia forces {using solid seismic masses}(G01P 15/14 takes precedence) • • by using non-electrical means • • • {by measuring the displacement of a movable inertial mass} • • • {for indicating angular accelerations (G01P 15/036 takes precedence)} • • • {for indicating predetermined acceleration values} • • • {by using fluidic means}
5/241 5/242 5/244 5/245 5/247 5/248 5/26	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} {involving pulsed waves} {by measuring transit time of acoustical waves (measuring propagation velocity of acoustical waves per se G01H 5/00)} {Sing-around-systems} {by measuring the direct influence of the streaming fluid on the properties of a detecting optical wave Measuring speed by integrating acceleration	15/001 15/003 15/005 15/006 15/008 15/02 15/03 15/032 15/034 15/036 15/038 15/04	Measuring shock, i.e. sudden change of acceleration • {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} • {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} • • {measuring translational acceleration} • {by making use of fluid seismic masses} • • {by using thermal pick-up} • by making use of inertia forces {using solid seismic masses}(G01P 15/14 takes precedence) • • by using non-electrical means • • {by measuring the displacement of a movable inertial mass} • • • {for indicating angular accelerations (G01P 15/036 takes precedence)} • • • {for indicating predetermined acceleration values} • • • {by using fluidic means} • • • {by using fluidic means}
5/241 5/242 5/244 5/245 5/247 5/248 5/26	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} {involving pulsed waves} {by measuring transit time of acoustical waves (measuring propagation velocity of acoustical waves per se G01H 5/00)} {Sing-around-systems} {by measuring the direct influence of the streaming fluid on the properties of a detecting optical wave Measuring speed by integrating acceleration (measuring travelled distance by double integration of	15/001 15/003 15/005 15/006 15/008 15/02 15/03 15/032 15/034 15/036 15/038	Measuring shock, i.e. sudden change of acceleration • {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} • {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} • • {measuring translational acceleration} • {by making use of fluid seismic masses} • • {by using thermal pick-up} • by making use of inertia forces {using solid seismic masses}(G01P 15/14 takes precedence) • • by using non-electrical means • • {by measuring the displacement of a movable inertial mass} • • • {for indicating angular accelerations (G01P 15/036 takes precedence)} • • • {for indicating predetermined acceleration values} • • • {by using fluidic means} • • • {by using maximum value} • • • using members subjected to a permanent
5/241 5/242 5/244 5/245 5/247 5/248 5/26 7/00	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} {involving pulsed waves} {by measuring transit time of acoustical waves (measuring propagation velocity of acoustical waves per se G01H 5/00)} {Sing-around-systems} {by measuring the direct influence of the streaming fluid on the properties of a detecting optical wave Measuring average value of speed (by determining time taken to traverse a fixed distance G01P 3/64, 	15/001 15/003 15/005 15/006 15/008 15/02 15/03 15/032 15/034 15/036 15/038 15/04 15/06	 Measuring shock, i.e. sudden change of acceleration {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} {measuring translational acceleration} {by making use of fluid seismic masses} {by using thermal pick-up} by making use of inertia forces {using solid seismic masses}(G01P 15/14 takes precedence) by using non-electrical means {by measuring the displacement of a movable inertial mass} {for indicating angular accelerations (G01P 15/036 takes precedence)} {for indicating predetermined acceleration values} {by using fluidic means} to indicating maximum value using members subjected to a permanent deformation
5/241 5/242 5/244 5/245 5/247 5/248 5/26 7/00	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} {involving pulsed waves} {by measuring transit time of acoustical waves (measuring propagation velocity of acoustical waves per se G01H 5/00)} {Sing-around-systems} {by measuring the direct influence of the streaming fluid on the properties of a detecting optical wave Measuring average value of speed (by determining time taken to traverse a fixed distance G01P 3/64, G01P 5/18) 	15/001 15/003 15/005 15/006 15/008 15/02 15/03 15/032 15/034 15/036 15/038 15/04 15/06	Measuring shock, i.e. sudden change of acceleration • {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} • {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} • • {measuring translational acceleration} • {by making use of fluid seismic masses} • • {by using thermal pick-up} • by making use of inertia forces {using solid seismic masses}(G01P 15/14 takes precedence) • • by using non-electrical means • • {by measuring the displacement of a movable inertial mass}} • • • {for indicating angular accelerations (G01P 15/036 takes precedence)} • • • {for indicating predetermined acceleration values} • • • {by using fluidic means} • • • {by using members subjected to a permanent deformation • • with conversion into electric or magnetic values
5/241 5/242 5/244 5/245 5/247 5/248 5/26 7/00	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} {involving pulsed waves} {by measuring transit time of acoustical waves (measuring propagation velocity of acoustical waves per se G01H 5/00)} {Sing-around-systems} {by measuring the direct influence of the streaming fluid on the properties of a detecting optical wave Measuring average value of speed (by determining time taken to traverse a fixed distance G01P 3/64, G01P 5/18) Measuring average speed of number of bodies, e.g. 	15/001 15/003 15/005 15/006 15/008 15/02 15/03 15/032 15/034 15/036 15/038 15/04 15/06	 Measuring shock, i.e. sudden change of acceleration {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} {measuring translational acceleration} {by making use of fluid seismic masses} {by using thermal pick-up} by making use of inertia forces {using solid seismic masses}(G01P 15/14 takes precedence) by using non-electrical means {by measuring the displacement of a movable inertial mass} {for indicating angular accelerations (G01P 15/036 takes precedence)} {for indicating predetermined acceleration values} {by using fluidic means} to indicating maximum value using members subjected to a permanent deformation
5/241 5/242 5/244 5/245 5/247 5/248 5/26 7/00 11/00	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} {involving pulsed waves} {by measuring transit time of acoustical waves (measuring propagation velocity of acoustical waves per se G01H 5/00)} {Sing-around-systems} {by measuring the direct influence of the streaming fluid on the properties of a detecting optical wave Measuring speed by integrating acceleration (measuring travelled distance by double integration of acceleration G01C 21/16) Measuring average value of speed (by determining time taken to traverse a fixed distance G01P 3/64, G01P 5/18) Measuring average speed of number of bodies, e.g. of vehicles for traffic control 	15/001 15/003 15/005 15/006 15/008 15/02 15/03 15/032 15/034 15/036 15/038 15/04 15/06	Measuring shock, i.e. sudden change of acceleration • {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} • {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} • • {measuring translational acceleration} • {by making use of fluid seismic masses} • • {by using thermal pick-up} • by making use of inertia forces {using solid seismic masses}(G01P 15/14 takes precedence) • • by using non-electrical means • • {by measuring the displacement of a movable inertial mass} • • • {for indicating angular accelerations (G01P 15/036 takes precedence)} • • • {for indicating predetermined acceleration values} • • • {by using fluidic means} • • • {by using maximum value} • • • using members subjected to a permanent deformation • • with conversion into electric or magnetic values • • {Details} • • {being provided with a particular type of spring-mass-system for defining the
5/241 5/242 5/244 5/245 5/247 5/248 5/26 7/00	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} {involving pulsed waves} {by measuring transit time of acoustical waves (measuring propagation velocity of acoustical waves per se G01H 5/00)} {Sing-around-systems} {by measuring the direct influence of the streaming fluid on the properties of a detecting optical wave Measuring speed by integrating acceleration (measuring travelled distance by double integration of acceleration G01C 21/16) Measuring average value of speed (by determining time taken to traverse a fixed distance G01P 3/64, G01P 5/18) Measuring average speed of number of bodies, e.g. of vehicles for traffic control Indicating or recording presence, absence, or 	15/001 15/003 15/005 15/006 15/008 15/02 15/03 15/032 15/034 15/036 15/038 15/04 15/06	Measuring shock, i.e. sudden change of acceleration • {by measuring acceleration changes by making use of a triple differentiation of a displacement signal } • {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} • • {measuring translational acceleration} • {by making use of fluid seismic masses} • • {by using thermal pick-up} • by making use of inertia forces {using solid seismic masses}(G01P 15/14 takes precedence) • • by using non-electrical means • • {by measuring the displacement of a movable inertial mass} • • • {for indicating angular accelerations (G01P 15/036 takes precedence)} • • • {for indicating predetermined acceleration values} • • • {by using fluidic means} • • • {by using maximum value} • • • using members subjected to a permanent deformation • • with conversion into electric or magnetic values • • {being provided with a particular type of spring-mass-system for defining the displacement of a seismic mass due to an
5/241 5/242 5/244 5/245 5/247 5/248 5/26 7/00 11/00	 using auto-correlation or cross-correlation detection means by measuring the direct influence of the streaming fluid on the properties of a detecting acoustical wave {by using reflection of acoustical waves, i.e. Doppler-effect} {involving continuous, e.g. modulated or unmodulated, waves (G01P 5/244 takes precedence)} {involving pulsed waves} {by measuring transit time of acoustical waves (measuring propagation velocity of acoustical waves per se G01H 5/00)} {Sing-around-systems} {by measuring the direct influence of the streaming fluid on the properties of a detecting optical wave Measuring speed by integrating acceleration (measuring travelled distance by double integration of acceleration G01C 21/16) Measuring average value of speed (by determining time taken to traverse a fixed distance G01P 3/64, G01P 5/18) Measuring average speed of number of bodies, e.g. of vehicles for traffic control 	15/001 15/003 15/005 15/006 15/008 15/02 15/03 15/032 15/034 15/036 15/038 15/04 15/06	Measuring shock, i.e. sudden change of acceleration • {by measuring acceleration changes by making use of a triple differentiation of a displacement signal} • {Kinematic accelerometers, i.e. measuring acceleration in relation to an external reference frame, e.g. Ferratis accelerometers (G01P 15/001, G01P 15/16, G01P 15/165 take precedence)} • • {measuring translational acceleration} • {by making use of fluid seismic masses} • • {by using thermal pick-up} • by making use of inertia forces {using solid seismic masses}(G01P 15/14 takes precedence) • • by using non-electrical means • • {by measuring the displacement of a movable inertial mass} • • • {for indicating angular accelerations (G01P 15/036 takes precedence)} • • • {for indicating predetermined acceleration values} • • • {by using fluidic means} • • • {by using maximum value} • • • using members subjected to a permanent deformation • • with conversion into electric or magnetic values • • {Details} • • {being provided with a particular type of spring-mass-system for defining the

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2015/0808 {for defining in-plane movement of the mass, i.e. movement of the mass in the plane of the substrate}	2015/088 2015/0882	 {for providing wafer-level encapsulation} {for providing damping of vibrations}
· · · · · · · · · · · · · · · · · · ·	15/0885	• • • {by magnetostrictive pick-up}
2015/0811 (for one single degree of freedom of	15/0888	• • • {for indicating angular acceleration}
movement of the mass}	15/0891	• • { with indication of predetermined acceleration
2015/0814 {for translational movement of the mass,		values (G01P 15/135 takes precedence)}
e.g. shuttle type}	15/0894	{by non-contact electron transfer, i.e. electron
2015/0817 { for pivoting movement of the mass,		tunneling}
e.g. in-plane pendulum}	15/0897	• • • {by thermal pick-up (<u>G01P 15/008</u> takes
2015/082 {for two degrees of freedom of movement	10,005,	precedence)}
of a single mass}	15/09	by piezoelectric pick-up
2015/0822 {for defining out-of-plane movement of the	15/0907	• • • { of the compression mode type }
mass}	15/0915	• • • { of the shear mode type }
2015/0825 {for one single degree of freedom of	15/0922	• • • {of the bending or flexing mode type}
movement of the mass}	15/093	
2015/0828 {the mass being of the paddle type being		• • by photoelectric pick-up
suspended at one of its longitudinal	15/097	by vibratory elements
ends}	15/0975	• • • • {by acoustic surface wave resonators or
2015/0831 {the mass being of the paddle type		delay lines}
having the pivot axis between the	15/10	• • • by vibratory strings
longitudinal ends of the mass, e.g. see-	15/105	by magnetically sensitive devices
saw configuration}	15/11	by inductive pick-up
	15/12	• • • by alteration of electrical resistance
2015/0834 {the mass constituting a pendulum	13/12	{(G01P 15/0897, G01P 15/105 take
having the pivot axis disposed		precedence)}
symmetrically between the longitudinal	15/121	• • • {by potentiometers}
ends, the center of mass being shifted		
away from the plane of the pendulum	15/122	• • • {by metal resistance strain gauges, e.g. wire
which includes the pivot axis}		resistance strain gauges}
2015/0837 {the mass being suspended so as to only	15/123	• • • {by piezo-resistive elements, e.g.
allow movement perpendicular to the		semiconductor strain gauges}
plane of the substrate, i.e. z-axis sensor}	15/124	• • • • {by semiconductor devices comprising at
2015/084 {the mass being suspended at more than		least one PN junction, e.g. transistors}
one of its sides, e.g. membrane-type	15/125	by capacitive pick-up
suspension, so as to permit multi-axis	15/13	by measuring the force required to restore a
movement of the mass}		proofmass subjected to inertial forces to a null
2015/0842 {the mass being of clover leaf shape}		position
2015/0845 {using a plurality of spring-mass	15/131	• • • {with electrostatic counterbalancing means}
systems being arranged on one common	15/132	• • • { with electromagnetic counterbalancing
planar substrate, the systems not being	10,102	means}
mechanically coupled and the sensitive	15/133	• • • • { with piezoelectric counterbalancing means }
direction of each system being different}	15/135	 by making use of contacts which are actuated
2015/0848 { using a plurality of mechanically coupled	13/133	by a movable inertial mass
spring-mass systems, the sensitive direction	15/14	
of each system being different}	15/14	• by making use of gyroscopes (gyroscopes per se
2015/0851 {using a plurality of spring-mass systems,		<u>G01C 19/00</u>)
each system having a different range of	15/16	• by evaluating the time-derivative of a measured
sensitivity to acceleration}		speed signal
	15/165	• • {for measuring angular accelerations}
	15/18	 in two or more dimensions
annular}	21/00	Testing on calibrating of amountury on devices
2015/0857 {using a particular shape of the suspension	21/00	Testing or calibrating of apparatus or devices
spring}		covered by the preceding groups
2015/086 {using a torsional suspension spring}	21/02	• of speedometers
2015/0862 {being provided with particular means being	21/025	• • {for measuring speed of fluids; for measuring
integrated into a MEMS accelerometer		speed of bodies relative to fluids (for measuring
structure for providing particular additional		volume flow <u>G01F 25/10</u>)}
functionalities to those of a spring mass		
system}		
2015/0865 {using integrated signal processing circuitry}		
2015/0868 {using self-test structures integrated into the		
microstructure}		
2015/0871 {using stopper structures for limiting the		
travel of the seismic mass}		
2015/0874 { using means for preventing stiction of the		
seismic mass to the substrate}		
2015/0877 {using integrated interconnect structures}		

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